

THE ASYMPTOTIC PROPERTIES OF ESTIMATES OF THE  
PARAMETERS OF A SINGLE EQUATION IN A COMPLETE  
SYSTEM OF STOCHASTIC EQUATIONS<sup>1, 2</sup>BY T. W. ANDERSON<sup>3</sup> AND HERMAN RUBIN<sup>4</sup>*Columbia University and Institute for Advanced Study*

**1. Summary.** In a previous paper [2] the authors have given a method for estimating the coefficients of a single equation in a complete system of linear stochastic equations. In the present paper the consistency of the estimates and the asymptotic distributions of the estimates and the test criteria are studied under conditions more general than those used in the derivation of these estimates and criteria. The point estimates, which can be obtained as maximum likelihood estimates under certain assumptions including that of normality of disturbances, are consistent even if the disturbances are not normally distributed and (a) some predetermined variables are neglected (Theorem 1) or (b) the single equation is in a non-linear system with certain properties (Theorem 2).

Under certain general conditions (normality of the disturbances not being required) the estimates are asymptotically normally distributed (Theorems 3 and 4). The asymptotic covariance matrix is given for several cases. The criteria derived in [2] for testing the hypothesis of over-identification have, asymptotically,  $\chi^2$ -distributions (Theorem 5). The exact confidence regions developed in [2] for the case that all predetermined variables are exogenous (that is, that the difference equations are of zero order) are shown to be consistent and to hold asymptotically even when this assumption is not true (Theorem 6).

**2. Introduction.** The complete system of linear stochastic equations considered by the authors in [2] was written

$$(2.1) \quad B_{yy}'y_t + \Gamma_{yz}'z_t = \epsilon_t',$$

where  $y_t$  is a row vector of  $G$  jointly dependent variables at "time"  $t$ ,  $z_t$  is a row vector of  $K$  variables predetermined at  $t$ , and  $\epsilon_t$  is a row vector of "disturbances," and  $B_{yy}$  and  $\Gamma_{yz}$  are matrices. If  $B_{yy}$  is non-singular the distribution of  $\epsilon_t$  induces the distribution of  $y_t$  given  $z_t$ .

One component equation of (2.1) was given special treatment. Let  $\beta$  be

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composed of the coefficients of the coordinates of  $y_t$  which are not assumed zero in the specified equation, and let  $x_t$  be composed of the corresponding components of  $y_t$ ; similarly let  $\gamma$  be composed of the coefficients of the coordinates of  $z_t$  which are not assumed zero, and  $u_t$  the corresponding components of  $z_t$ ; and let  $\zeta_t$  be the component of  $\epsilon_t$  associated with the specified equation. Then the single equation is

$$(2.2) \quad \beta x'_t + \gamma u'_t = \zeta_t.$$

Suppose we have a set of observations  $x_t, z_t, t = 1, \dots, T$ . For sets of any two vectors  $a_t$  and  $b_t$ , let the second-order moment matrix be

$$(2.3) \quad M_{ab} = \frac{1}{T} \sum_{t=1}^T a'_t b_t.$$

Let  $s_t$  be some linear transform of  $v_t$ , the set of coordinates of  $z_t$  not contained in  $u_t$ , chosen so  $M_{su} = 0$ . Defining

$$(2.4) \quad W_{xx} = M_{xx} - M_{xz} M_{zz}^{-1} M_{zx},$$

and assuming  $\epsilon_t$  normally distributed with mean 0, covariance matrix  $\Sigma$ , and independently of  $\epsilon_{t'} (t \neq t')$ , we find  $\hat{\beta}$ , the maximum likelihood estimate of  $\beta$ , to be proportional to a vector defined by

$$(2.5) \quad (M_{zs} M_{ss}^{-1} M_{sz} - \nu W_{xx}) b' = 0,$$

taking  $\nu$  as the smallest root of

$$(2.6) \quad |M_{zs} M_{ss}^{-1} M_{sz} - \nu W_{xx}| = 0.$$

The vector is normalized by

$$(2.7) \quad \hat{\beta}' \hat{\Phi}_{xx} \hat{\beta} = 1,$$

where  $\hat{\Phi}_{xx}$  may be a function of the estimates of other parameters. The estimate of  $\gamma$  is  $\hat{\gamma} = -\hat{\beta}' M_{xu} M_{uu}^{-1}$  [2; Theorem 1]. These estimates were derived under the following explicit Assumptions A, B, C, and D:

ASSUMPTION A. *The selected structural equation (2.2) is one equation of a complete linear system of stochastic equations. It is identified by the fact that if  $H$  is the number of coordinates in  $x_t$ , there are at least  $H - 1$  coordinates in  $v_t$ , the vector of predetermined variables in the system, but missing in (2.2).*

ASSUMPTION B. *At time  $t$  all of the coordinates of  $z_t = (u_t, v_t)$  are given.*

ASSUMPTION C. *The coordinates of  $z_t$  are given functions of exogenous variables and of coordinates of  $y_{t-1}, y_{t-2}, \dots$ . If coordinates of  $y_0, y_{-1}, \dots$  are involved in  $z_t$ , they will be considered as given numbers. The moment matrix  $M_{zz}$  is non-singular with probability one.*

ASSUMPTION D. *The disturbance vectors  $\epsilon_t$  are distributed serially independently and normally with mean zero and covariance matrix  $\Sigma_{zz}$ .*

Under these assumptions it is found that  $(1 + \nu)^{-1T}$  is the likelihood ratio

criterion for testing the hypothesis that the number of components of  $z_t$  assumed to have zero coefficients is so great.

If there are no lagged endogenous variables in  $z_t$ , we can find confidence regions for  $\beta$  and for  $\beta$  and  $\gamma$  simultaneously as well as an approximate test for the above hypothesis. The assumptions used for these results are A, B, and

ASSUMPTION E. *All the coordinates of  $z_t = (u_t, v_t)$  are exogenous. The moment matrix  $M_{zz}$  is non-singular. The disturbances of the selected equation are distributed independently and normally with mean zero and variance  $\sigma^2$ .*

Assumptions A and B are used in this paper and a number in addition, which will be lettered similarly. It is to be emphasized that the various assumptions are used alternatively, never all at once; in fact many assumptions are mutually exclusive.

**3. Consistency of the estimates.** The estimates  $\hat{\beta}$  and  $\hat{\gamma}$  are consistent not only in the case for which they are maximum likelihood estimates, but also in cases in which the disturbances are not normally or even identically distributed. Moreover, for consistency of the estimates it is not necessary that the investigator know all of the components of  $v_t$  or use them. Another direction in which the assumptions may be relaxed is to permit the other equations in the system to be non-linear.

3.1. *The linear case.* This case is characterized by Assumption A. We need also to assume:

ASSUMPTION F.  *$M_{zz}$  converges to a fixed non-singular limit  $R$  in probability.*

Let  $u_t$  consist of the part of  $z_t$  that enters the selected structural equation (22). The remainder of the components of  $z_t$  are divided into two groups as to whether they are known or not. Let  $c_t$  be a linear transform of the known components not entering the specified equation such that

$$(3.1) \quad \text{plim}_{t \rightarrow \infty} M_{uc} = 0,$$

and let  $r_t$  be a linear transform of the components of  $z_t$  not known such that

$$(3.2) \quad \text{plim}_{t \rightarrow \infty} M_{ur} = 0,$$

$$(3.3) \quad \text{plim}_{t \rightarrow \infty} M_{cr} = 0.$$

The relevant part of the "reduced form," obtained from (2.1) by multiplication by  $B_{yy}^{-1}$  is

$$(3.4) \quad x'_t = \bar{\Pi}_{xu}u'_t + \Pi_{xc}c'_t + \Pi_{xr}r'_t + \delta'_t.$$

The matrix  $(\Pi_{xc}\Pi_{xr})$  is  $\Pi_{xs}$  (defined in [2]) multiplied on the right by a non-singular matrix; hence,  $\beta\Pi_{xc} = 0$ , and similarly  $\beta\bar{\Pi}_{xu} = \gamma$ . We shall find it convenient to assume

ASSUMPTION G.  *$\Pi_{xc}$  has rank  $H - 1$ .*

This means that for  $T$  sufficiently large the probability is arbitrarily near 1 that (2.2) is identified.

However, these conditions still do not insure consistency. We need the asymptotic analogue of lack of correlation:

ASSUMPTION H.

$$\text{plim}_{T \rightarrow \infty} \frac{1}{T} \sum_{t=1}^T \delta'_t z_t = 0.$$

We do not need to require that the covariance matrices of  $\delta_t$  are the same or even that they exist. We shall make an assumption about

$$(3.5) \quad W_{zz}^* = M_{zz} - (M_{zu} M_{zc}) \begin{pmatrix} M_{uu} & M_{uc} \\ M_{cu} & M_{cc} \end{pmatrix}^{-1} \begin{pmatrix} M_{uz} \\ M_{cz} \end{pmatrix}.$$

ASSUMPTION I. *The ratio of the largest to the smallest characteristic roots of  $W_{zz}^*$  is bounded in probability.*

This means that for a suitable constant  $K$

$$(3.6) \quad \lim_{T \rightarrow \infty} P \left( \frac{l(W_{zz}^*)}{s(W_{zz}^*)} > K \right) = 0,$$

where  $P(E)$  denotes the probability of event  $E$  and  $s(A)$  and  $l(A)$  are the smallest and largest roots of the matrix  $A$ , respectively.

Assumptions F and H imply that  $P_{zu} \rightarrow \bar{\Pi}_{zu}$  and  $P_{zc} \rightarrow \bar{\Pi}_{zc}$  in probability, where  $P_{zu} = M_{zu} M_{uu}^{-1}$  and  $P_{zc}$  is the part of

$$(3.7) \quad (M_{zu} M_{zc}) \begin{pmatrix} M_{uu} & M_{uc} \\ M_{cu} & M_{cc} \end{pmatrix}^{-1}$$

corresponding to the vector<sup>5</sup>  $c_t$ . The first assertion follows because  $M_{zu} M_{uu}^{-1} = (\bar{\Pi}_{zu} M_{uu} + \bar{\Pi}_{zc} M_{zc} + \bar{\Pi}_{zr} M_{ru} + M_{\delta u}) M_{uu}^{-1}$  and  $M_{zc} \rightarrow 0$ ,  $M_{ru} \rightarrow 0$ , and  $M_{\delta u} \rightarrow 0$  in probability by (3.1), (3.3) and Assumption H; the second assertion follows similarly. Since matrix multiplication is continuous, and the characteristic roots of a matrix are continuous functions of the matrix,<sup>6</sup>

$$(3.8) \quad \text{plim}_{T \rightarrow \infty} s[P_{zc} M_{ss} P'_{zc}] = 0,$$

where  $M_{ss} = (M_{cc} - M_{cu} M_{uu}^{-1} M_{uc})$ . This follows from the well-known theorem (a proof of which is given in [4]) that if a random vector  $X_T$  converges stochastically to  $X$ , then  $f(X_T)$  converges stochastically to  $f(X)$  if  $f(y)$  is continuous at  $X$ .

We shall find the following lemmas convenient. The proofs are simple and have been given in [1].

LEMMA 1. *Let  $B$  be positive definite,  $A$  positive semi-definite. Then the smallest root  $\nu$  of  $|A - \nu B| = 0$  is less than or equal to  $s(A)/s(B)$ .*

<sup>5</sup> See Section 4 of [2].

<sup>6</sup> Because of the assertion above and Assumptions F and G only one characteristic root of the matrix approaches zero in probability.

LEMMA 2. *Each element of a positive definite matrix is less in absolute value than the largest characteristic root.*

Let  $\nu$  be the smallest root of

$$(3.9) \quad |P_{zc}M_{ss}P'_{zc} - \nu W_{zz}^*| = 0.$$

Then  $\text{plim}_{T \rightarrow \infty} \nu W_{zz}^* = 0$ . This statement follows from (3.8) and Lemmas 1 and 2.

Since 0 is a simple characteristic root of  $\Pi_{xc} \text{plim}_{T \rightarrow \infty} M_{ss} \Pi'_{xc}$ , it follows from (3.9) and the consistency of  $P_{zu}$  and  $P_{zc}$  that  $\hat{\beta}$  approaches  $\beta$  apart from normalization. The following theorem results directly:

THEOREM 1. *Under Assumptions A, F, G, H, and I, and if  $\text{plim}_{T \rightarrow \infty} \beta \hat{\Phi}_{zz} \beta' = 1$ ,*

$$(3.10) \quad \text{plim}_{T \rightarrow \infty} \hat{\beta} = \beta,$$

$$(3.11) \quad \text{plim}_{T \rightarrow \infty} \hat{\gamma} = \gamma,$$

where  $\hat{\beta}$  and  $\hat{\gamma}$  are calculated as if  $r_t = 0$  and as if the remainder of A, B, C, and D were satisfied.<sup>7</sup>

3.2. *The non-linear case.* In this section we apply the estimates obtained in [2] to an equation of a complete system in which the remaining equations may be non-linear. We replace Assumption A by the following assumption:

ASSUMPTION J. *The selected structural equation (2.2) is one equation of a complete system of stochastic equations:*

$$(3.11) \quad F_i(y_t, z_t) = \epsilon_i \quad (i = 1, \dots, G).$$

Let us solve the complete system (3.11) for the components of  $y_t$ . We obtain

$$(3.12) \quad y_{ti} = h_j(z_t, \epsilon_t).$$

Let  $u_t$  be the subvector of  $z_t$  occurring in the selected structural equation. Let  $c_t$  be a vector function of  $z_t$  such that  $\text{plim}_{T \rightarrow \infty} M_{cu} = 0$ . We may write (3.12)

for those  $y$ 's occurring in the selected structural equation as

$$(3.13) \quad x'_t = \bar{\Pi}_{zu} u'_t + \Pi_{zc} c'_t + \varphi'(z_t, \epsilon_t),$$

where the components of  $\varphi(z_t, \epsilon_t)$  are the residuals from the formal limiting regression of  $x_t$  on  $u_t$  and  $c_t$ . The proof of Theorem 1 can be used to prove the following:

THEOREM 2. *If Assumptions F, G, H, I, and J are satisfied with  $z_t$  replaced by  $(u_t, c_t)$  and  $\delta_t$  replaced by  $\varphi(z_t, \epsilon_t)$ , and  $\tau_t = 0$ , and if  $\text{plim}_{T \rightarrow \infty} \beta \hat{\Phi}_{zz} \beta' = 1$ , then*

$$(3.14) \quad \text{plim}_{T \rightarrow \infty} \hat{\beta} = \beta,$$

$$(3.15) \quad \text{plim}_{T \rightarrow \infty} \hat{\gamma} = \gamma.$$

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<sup>7</sup> This follows from the above statements because  $\hat{\beta}$  and  $\hat{\gamma}$  are (vector-valued) rational functions of  $M_{zz}$ ,  $P_{zs}$ ,  $W_{zz}^*$  and  $\Phi_{zz}$  which approach limits in probability.

**4. The asymptotic distribution of the estimates.**

4.1. *The asymptotic distribution of  $P_{zs}$  and  $P_{zu}$ .* To obtain the asymptotic distribution of the estimates we need stronger assumptions. Throughout Sections 4.1 and 4.2 we use Assumptions A, B, F, II, I, and the following:

ASSUMPTION K. *The exogenous variables are bounded; the vector of disturbances of the complete system has mean zero, and is serially independent; for some  $\lambda > 0$  and some  $M$ ,  $\mathfrak{E}(|\delta_{ti}|^{4+\lambda}) < M$ ; the coordinates of  $z_t$  may be linear combinations of lagged endogenous variables. If the endogenous part of a coordinate is*

$$\sum_{\tau=1}^{\infty} \sum_{i=1}^G g_{\tau i} y_{t-\tau, i},$$

then

$$\sum_{\tau=1}^{\infty} \sum_{i=1}^G |g_{\tau i}| < \infty$$

and

$$\sum_{\tau=t}^{\infty} \sum_{i=1}^G g_{\tau i} y_{t-\tau, i}$$

is bounded.

ASSUMPTION L. *The matrix  $\Phi_{zz}$  is known and constant.*

ASSUMPTION M. *For each  $i, j, k, l, 1 \leq i, j \leq H, 1 \leq k, l \leq K,$*

$$\lim_{T \rightarrow \infty} \frac{1}{T} \sum_{t=1}^T \mathfrak{E}(\delta_{ti} \delta_{tj} z_{tk} z_{tl}) = \kappa_{ijkl}$$

exists.

Let the components of  $M_{yy}, M_{yz}, M_{zz}$  be arranged as a vector  $m(T)$  with mean value  $\mu(T)$ . It has been shown [3] that  $\sqrt{T}(m(T) - \mu(T))$  is asymptotically distributed according to  $N(0, \Sigma)$ , the normal distribution with mean 0 and covariance matrix  $\Sigma$  composed of elements

$$\sigma_{ij} = \lim_{T \rightarrow \infty} \mathfrak{E}(T[m_i(T) - \mu_i(T)] [m_j(T) - \mu_j(T)]).$$

In conjunction with this result we make repeated use of a special case of Theorem 6 of [4]:

Suppose  $\sqrt{T}(x_{jT} - \xi_{jT})$  ( $j = 1, \dots, n$ ) have the joint asymptotic distribution  $N(0, \Psi)$  with  $\xi_{jT}$  being functions of  $T$  such that  $\lim_{T \rightarrow \infty} \xi_{jT} = \xi_j$ . Let  $f_{kT}(z_1, \dots, z_n)$

be random Borel-measurable functions of  $n$  real variables such that  $\frac{\partial f_{kT}}{\partial z_j} = \alpha_{kjT}(z)$

exists with probability one for  $T$  sufficiently large and  $z$  in a fixed neighborhood of  $\xi$ , and suppose that there exist numbers  $\alpha_{kj}$  such that for any  $\epsilon > 0$ , and  $\lambda > 0$ ,  $P(\sup_{(z-\xi_T)(z-\xi_T)' \leq (N/T)} |\alpha_{kjT}(z) - \alpha_{kj}| > \epsilon)$  approaches zero. Then if

$y_{kT} = f_{kT}(x_{1T}, \dots, x_{nT})$  and  $\eta_{kT} = f_{kT}(\xi_{1T}, \dots, \xi_{nT})$ , the random variables  $\sqrt{T}(y_{kT} - \eta_{kT})$  have the joint asymptotic distribution  $N(0, A\Psi A')$ , where  $A = (\alpha_{ij})$ .

To obtain the asymptotic distributions we have only to verify that the assumptions of this statement are satisfied, and compute  $A$ , since the asymptotic distribution is characterized completely by  $A\Psi A'$ . We shall denote the element in the  $k$ -th row and  $l$ -th column of  $A\Psi A'$  by  $\sigma(f_k, f_l)$ . We shall find it convenient to use the notation  $df = Adx$ ; that is, the differential  $df$  is defined in terms of the limit matrix  $A$ .

Let

$$(4.1) \quad A = M_{bu},$$

$$(4.2) \quad B = M_{bs},$$

$$(4.3) \quad C = \text{plim}_{T \rightarrow \infty} M_{uu},$$

$$(4.4) \quad E = \text{plim}_{T \rightarrow \infty} M_{ss},$$

$$(4.5) \quad L = P_{zu},$$

$$(4.6) \quad P = P_{zs} = M_{zs}M_{ss}^{-1},$$

$$(4.7) \quad \Lambda = \bar{\Pi}_{zu},$$

$$(4.8) \quad \Pi = \Pi_{zs}.$$

The matrix  $L$  is the random function  $AM_{uu}^{-1} + \Pi_{zc}M_{cu}M_{uu}^{-1} + \Lambda$  of  $A$ ,  $P$  is the random function  $BM_{ss}^{-1} + \Pi$  of  $B$ . Then

$$(4.9) \quad dL = (dA)C^{-1},$$

$$(4.10) \quad dP = (dB)E^{-1}.$$

However

$$(4.11) \quad \sigma(a_{ik}, a_{jl}) = \alpha_{ijkl},$$

$$(4.12) \quad \sigma(a_{ik}, b_{jl}) = \beta_{ijkl},$$

$$(4.13) \quad \sigma(b_{ik}, b_{jl}) = \gamma_{ijkl},$$

where  $\alpha_{ijkl}$ ,  $\beta_{ijkl}$ ,  $\gamma_{ijkl}$  are the appropriate quantities  $\kappa_{abcd}$ , respectively. From these we may compute  $\sigma(l_{ij}, l_{kl})$ ,  $\sigma(l_{ij}, p_{kl})$ , and  $\sigma(p_{ij}, p_{kl})$ , the elements of the asymptotic covariance matrix of the elements of  $L$  and  $P$  (which are asymptotically normally distributed by the above). These elements can be estimated consistently from the sample (the proof follows from Theorem 1).

4.2. *The asymptotic distribution of  $\hat{\beta}$  and  $\hat{\gamma}$  for constant normalization.* In this section we shall show that  $\hat{\beta}$  and  $\hat{\gamma}$  are asymptotically normally distributed (Theorem 3). In view of the above theorem on asymptotic distributions the intricate part of the proof is in obtaining the covariance matrix. First we shall demonstrate that the elements of  $\nu W$  are  $o(1/\sqrt{T})$  in probability. Since Assumption I holds, it is sufficient to show that  $s(P_{zs}M_{ss}P'_{zs})$  is  $o(1/\sqrt{T})$  in probability. This means  $d | P_{zs}M_{ss}P'_{zs} | = 0$ , since each of the characteristic roots of  $P_{zs}M_{ss}P'_{zs}$  except the smallest approaches a non-zero limit in probability.

For any matrix  $A$ ,  $A_{ij}$  denotes the matrix obtained by deleting the  $i$ -th row and  $j$ -th column from  $A$ , and  $A_{ik,jl}$  is the matrix obtained by deleting the  $i$ -th and  $k$ -th rows and the  $j$ -th and  $l$ -th columns. Let

$$A^{ij} = (-1)^{i+j} |A_{ij}|,$$

$$A^{ijk,l} = (-1)^{i+j+k+l+\epsilon} |A_{ik,jl}|,$$

where  $\epsilon = 0$  if  $(i - k)(j - l) > 0$ , 1 otherwise when  $i \neq k, j \neq l$ .  $A^{ijk,l} = 0$  if  $i = k$  or  $j = l$ . In the rest of the paper we use the summation convention of tensor calculus for lower case indices; namely, that whenever a lower case letter appears as a superscript and a subscript in an expression, the corresponding terms are to be summed on that index.

In general

$$(4.14) \quad d|A| = A^{ij} da_{ij}.$$

We may consider  $P_{xs}M_{ss}P'_{zs}$  as a random function of  $P_{xs}$ . Then

$$(4.15) \quad d(i,j\text{-th element of } P_{xs}M_{ss}P'_{zs}) = \pi_i^k e_{k,l} dp_j^l + \pi_j^l e_{k,l} dp_i^k.$$

However

$$(4.16) \quad (\Pi_{xs}E\Pi'_{zs})^{ij} = \rho^j \beta^i = \rho^i \beta^j,$$

where  $\rho^i$  is a factor of proportionality. Since  $\beta \Pi_{xs} = 0$ , we have  $d|P_{xs}M_{ss}P'_{zs}| = 0$ .

Then it can be shown that  $d(\hat{\Pi}_{xs}M_{ss}\hat{\Pi}'_{zs} - P_{xs}M_{ss}P'_{zs}) = 0$ , where  $\hat{\Pi}_{xs} = \left(I - \frac{W_{xx}\hat{\beta}'\hat{\beta}}{\hat{\beta}W_{xx}\hat{\beta}'}\right)P_{xs}$ .

Let  $\Theta = \Pi_{xs}E\Pi'_{zs}$  and  $F = P_{xs}M_{ss}P'_{zs}$ . We know that  $\hat{\beta}_i = \hat{\rho}_j \Theta^{ij}$ , where  $\rho_j = 1/\rho^j$  (and the capital letter  $J$  indicates that there is not to be a sum on that index), and  $\hat{\Theta} = \hat{\Pi}_{xs}M_{ss}\hat{\Pi}'_{zs}$ . Hence

$$(4.17) \quad d\hat{\beta}^i = \rho_j d\hat{\Theta}^{ij} + \Theta^{ij} d\hat{\rho}_j.$$

However  $\hat{\beta}^i \hat{\beta}^j \varphi_{ij} = 1$ ; therefore  $\hat{\rho}_j = (\hat{\Theta}^{ij} \hat{\Theta}^{kj} \varphi_{ik})^{-1}$ . From this it follows that

$$(4.18) \quad d\hat{\rho}_j = -(\hat{\rho}_j)^3 \Theta^{ij} \varphi_{ik} d\hat{\Theta}^{kj}.$$

From (4.14) we see  $d\hat{\Theta}^{kj} = \Theta^{kj, \alpha\beta} d\hat{\theta}_{\alpha\beta}$ . Therefore

$$(4.19) \quad d\hat{\beta}^i = \rho_j [\Theta^{ij, \alpha\beta} - \beta^i \beta^l \Theta^{kj, \alpha\beta} \varphi_{kl}] d\hat{\theta}_{\alpha\beta}.$$

Let us define  $\psi_j = \beta^i \varphi_{ij}$ . Let us multiply (4.19) by  $\theta_{\gamma i}$  and  $\psi_i$ . We obtain

$$(4.20) \quad \theta_{\gamma i} d\hat{\beta}^i = \rho_j \theta_{\gamma i} \Theta^{ij, \alpha\beta} d\hat{\theta}_{\alpha\beta}$$

$$= \rho_j \delta_{\gamma}^J \Theta^{\alpha\beta} d\hat{\theta}_{\alpha\beta} - \rho_j \Theta^{J\beta} d\hat{\theta}_{\gamma\beta} = -\beta^\alpha d\hat{\theta}_{\gamma\alpha},$$

$$(4.21) \quad \psi_i d\hat{\beta}^i = 0.$$

Let us simplify (4.20). We see that

$$(4.22) \quad \beta^\alpha d\hat{\theta}_{\gamma\alpha} = \beta^\alpha \pi_{\gamma}^k e_{k,l} dp_\alpha^l.$$

Hence

$$(4.23) \quad \begin{aligned} \sigma(\beta^\alpha d\hat{\theta}_{\gamma\alpha}, \beta^\mu d\hat{\theta}_{\gamma\mu}) &= \beta^\alpha \pi_\gamma^k e_{ki} \beta^\mu \pi_\gamma^l e_{lj} e^{lm} e^{ji} \gamma_{\alpha\mu i} \\ &= \beta^\alpha \beta^\mu \pi_\gamma^m \pi_\gamma^i \gamma_{\alpha\mu i} = r_{1\gamma\gamma}, \end{aligned}$$

say. Let  $\sigma(\hat{\beta}^i, \hat{\beta}^j) = q_1^{ij}$ , and let  $Q_1 = (q_1^{ij})$ . Then from (4.20) and (4.23) we obtain

$$(4.24) \quad \Theta Q_1 \Theta = R_1,$$

and (4.21) is

$$(4.25) \quad \psi Q_1 = 0.$$

It may be shown (see [1], for example) that the solution is

$$(4.26) \quad Q_1 = (I - \beta' \psi)_{.k} (\Theta_{kk})^{-1} (R_1)_{kk} (\Theta_{kk})^{-1} (I - \psi' \beta)_k,$$

where  $k(1 \leq k \leq H)$  is arbitrary except that  $\beta^k \neq 0$ , and  $A_{.k}$  denotes  $A$  with the  $k$ -th column deleted, etc. If the normalization is  $\beta^i = 1, k = i$  is a convenient choice.

Since  $\hat{\gamma} = -\hat{\beta}L$ ,

$$(4.27) \quad d\hat{\gamma}^m = -d\hat{\beta}^i \lambda_i^m - \beta^i d l_i^m.$$

Hence

$$(4.28) \quad \sigma(\hat{\beta}^j, \hat{\gamma}^m) = -\sigma(\hat{\beta}^j, \hat{\beta}^i) \lambda_i^m - \sigma(\hat{\beta}^j, l_i^m) \beta^i,$$

$$(4.29) \quad \sigma(\hat{\gamma}^m, \hat{\gamma}^n) = \sigma(\hat{\beta}^j, \hat{\beta}^i) \lambda_i^m \lambda_j^n + \sigma(\hat{\beta}^j, l_i^m) \beta^i \lambda_j^n + \sigma(\hat{\beta}^j, l_i^n) \beta^i \lambda_j^m + \sigma(l_i^m, l_j^n) \beta^i \beta^j.$$

We, therefore, see that we must compute  $\sigma(\hat{\beta}^j, l_i^m) \beta^i$  and  $\sigma(l_i^m, l_j^n) \beta^i \beta^j$ . We find, from (4.20), (4.21), and (4.22) that

$$(4.30) \quad \theta_{\gamma j} \beta^i \sigma(\hat{\beta}^j, l_i^m) = -\beta^i \beta^j \pi_j^k c^{mp} \beta_{iipk} = r_{2\gamma}^m,$$

say. Let  $(\sigma(\hat{\beta}^j, l_i^m) \beta^i) = Q_2$ , and let  $R_2 = (r_{2\gamma}^m)$ . Then, from (4.30) and (4.21) we obtain

$$(4.31) \quad \Theta Q_2 = R_2,$$

$$(4.32) \quad \psi Q_2 = 0.$$

The solution is

$$(4.33) \quad Q_2 = (I - \beta' \psi)_{.k} (\Theta_{kk})^{-1} (R_2)_{.k}.$$

We find, readily, that

$$(4.34) \quad \beta^i \beta^j \sigma(l_i^m, l_j^n) = \beta^i \beta^j c^{mp} c^{nq} \alpha_{ijpq} = q_3^{mn},$$

say, where  $(c^{mp}) = C^{-1}$ . Let  $Q_3 = (q_3^{mn})$ . This concludes the proof of Theorem 3.

**THEOREM 3.** *If Assumptions A, B, F, II, I, K, L, and M are satisfied,  $\sqrt{T}(\hat{\beta} - \beta)$  and  $\sqrt{T}(\hat{\gamma} - \gamma)$  are asymptotically jointly normally distributed with means zero and covariance matrix*

$$(4.35) \quad \sigma(\hat{\beta}', \hat{\beta}) = Q_1,$$

$$(4.36) \quad \sigma(\hat{\beta}', \hat{\gamma}) = -Q_2 \bar{\Pi}_{xu} - Q_2,$$

$$(4.37) \quad \sigma(\hat{\gamma}', \hat{\gamma}) = \bar{\Pi}'_{xu} Q_1 \bar{\Pi}_{xu} + \bar{\Pi}'_{xu} Q_2 + Q_2' \bar{\Pi}_{xu} + Q_3,$$

where  $Q_1$  is given by (4.26),  $Q_2$  by (4.33), and  $Q_3$  by (4.34).

If there is a kind of asymptotic independence of  $\zeta_t$  and  $z_t$ , then the above expressions may be simplified. Corollary 1 results from Theorem 3 and the following assumption:

ASSUMPTION N.  $\lim_{T \rightarrow \infty} \frac{1}{T} \sum_{t=1}^T \mathcal{E}(\zeta_t^2 z_t' z_t) = \sigma^2 R$ , where  $R$  is defined in Assumption F.

COROLLARY 1. If Assumptions A, B, F, II, I, K, L, M, and N are satisfied,  $\sqrt{T}(\hat{\beta} - \beta)$  and  $\sqrt{T}(\hat{\gamma} - \gamma)$  are asymptotically jointly normally distributed with means zero and covariance matrix

$$(4.38) \quad \sigma(\hat{\beta}', \hat{\beta}) = \sigma^2 (I - \beta' \psi)_{\cdot k} (\Theta_{kk})^{-1} (I - \psi' \beta)_{k \cdot},$$

$$(4.39) \quad \sigma(\hat{\beta}', \hat{\gamma}) = -\sigma^2 (I - \beta' \psi)_{\cdot k} (\Theta_{kk})^{-1} (\bar{\Pi}_{xu} + \psi' \gamma)_{k \cdot},$$

$$(4.40) \quad \sigma(\hat{\gamma}', \hat{\gamma}) = \sigma^2 [(\bar{\Pi}'_{xu} + \gamma' \psi)_{\cdot k} (\Theta_{kk})^{-1} (\bar{\Pi}_{xu} + \psi' \gamma)_{k \cdot} + C^{-1}].$$

4.3. *Asymptotic distribution of the estimates of the parameters  $\beta$  and  $\gamma$  with normalization a function of  $\Omega_{xx}$ .*

If we relax Assumption L that  $\Phi_{xx}$  is constant, we obtain a more general result. Since the proof, however, is more involved, we shall not give it here; the reader is referred to [1]. In the derivation of the estimates  $\Omega_{xx}$  was defined as  $\mathcal{E}(\delta_t' \delta_t)$ . In the asymptotic theory we do not assume that this is the same for each  $t$ . We use the following assumption:

$$\text{ASSUMPTION O.} \quad \lim_{T \rightarrow \infty} \frac{1}{T} \sum_{t=1}^T \mathcal{E}(\delta_{ti} \delta_{tj} \delta_{tk} z_{tl}) = n_{ijkl} \text{ exists;}$$

$$\lim_{T \rightarrow \infty} \frac{1}{T} \sum_{t=1}^T \mathcal{E}(\delta_{ti} \delta_{tj}) = \bar{\omega}_{ij} \text{ exists;}$$

$$\lim_{T \rightarrow \infty} \frac{1}{T} \sum_{t=1}^T \mathcal{E}(\delta_{ti} \delta_{tj} \delta_{tk} \delta_{tl}) = \bar{\omega}_{ijkl} + \bar{\omega}_{ij} \bar{\omega}_{kl} \text{ exists.}$$

Let  $\delta_{ijkl}$  be the quantities  $n_{ijkl}$  corresponding to the  $u$ 's,  $\epsilon_{ijkl}$ , the quantities corresponding to the  $c$ 's. Define

$$(4.41) \quad \chi^{ij} = \frac{1}{2} \beta^k \beta^l \frac{\partial \varphi_{kl}}{\partial \omega_{ij}},$$

$$(4.42) \quad r_{4\gamma} = \beta^k \pi_\gamma^l \chi^{ij} \epsilon_{ijkl},$$

$$(4.43) \quad q_4' = (I - \beta' \psi)_{\cdot k} (\Theta_{kk})^{-1} (r_4')_{k \cdot},$$

$$(4.44) \quad q_5 = \chi^{ij} \chi^{kl} \bar{\omega}_{ijkl},$$

$$(4.45) \quad q_6^k = \chi^{ij} \beta^m \delta_{ijml} c^{kl}.$$

With the aid of the matrices  $Q_1$ ,  $Q_2$ , and  $Q_3$ , the vectors  $q_4$  and  $q_6$ , and the

scalar  $q_5$ , we may express the asymptotic covariance matrix of the estimates. We obtain

THEOREM 4. *If Assumptions A, B, F, H, I, K, M, and O are satisfied, and  $\Phi_{xx}$  is a function of  $\Omega_{xx}$ ,  $\sqrt{T}(\hat{\beta} - \beta)$  and  $\sqrt{T}(\hat{\gamma} - \gamma)$  are asymptotically jointly normally distributed with means zero and covariance matrix*

$$(4.46) \quad \sigma(\hat{\beta}', \hat{\beta}) = Q_1 + q_4' \beta + \beta' q_4 + q_5 \beta' \beta,$$

$$(4.47) \quad \sigma(\hat{\beta}', \hat{\gamma}) = -Q_1 \bar{\Pi}_{xu} + q_4' \gamma - \beta' q_4 \bar{\Pi}_{xu} + q_5 \beta' \gamma - Q_2 - \beta' q_6,$$

$$(4.48) \quad \begin{aligned} \sigma(\hat{\gamma}', \hat{\gamma}) &= \bar{\Pi}'_{xu} Q_1 \bar{\Pi}_{xu} - \bar{\Pi}'_{xu} q_4' \gamma - \gamma' q_4 \bar{\Pi}_{xu} + q_5 \gamma' \gamma \\ &\quad + \bar{\Pi}'_{xu} Q_2 + Q_2' \bar{\Pi}_{xu} - \gamma' q_6 - q_6' \gamma + Q_3, \end{aligned}$$

where  $Q_1, Q_2, Q_3, q_4, q_5$ , and  $q_6$  are given by (4.26), (4.33), (4.34), (4.43), (4.44), and (4.45) respectively.

COROLLARY 2. *If Assumptions A, B, D, F, H and K are satisfied, and  $\Phi_{xx} = \Omega_{xx}$ ,  $\sqrt{T}(\hat{\beta} - \beta)$  and  $\sqrt{T}(\hat{\gamma} - \gamma)$  are asymptotically jointly normally distributed with means zero and covariance matrix*

$$(4.49) \quad \sigma(\hat{\beta}', \hat{\beta}) = (I - \beta' \psi)_{.k} (\Theta_{kk})^{-1} (I - \psi' \beta)_{.k} + \frac{1}{2} \beta' \beta,$$

$$(4.50) \quad \sigma(\hat{\beta}', \hat{\gamma}) = -(I - \beta' \psi)_{.k} (\Theta_{kk})^{-1} (\bar{\Pi}_{xu} + \psi' \gamma)_{.k} + \frac{1}{2} \beta' \gamma,$$

$$(4.51) \quad \sigma(\hat{\gamma}', \hat{\gamma}) = (\bar{\Pi}'_{xu} + \gamma' \psi)_{.k} (\Theta_{kk})^{-1} (\bar{\Pi}_{xu} + \psi' \gamma)_{.k} + C^{-1} + \frac{1}{2} \gamma' \gamma.$$

5. Asymptotic distribution of the likelihood ratio criterion and the small sample criterion for testing a certain hypothesis. The likelihood ratio criterion for testing the hypothesis that the number of coordinates of  $z_t$  with zero coefficients in the selected structural equation is as great as it is assumed to be is  $(1 + \nu)^{-1/2} T$  [2, Theorem 2], where  $\nu$  is the smallest root of

$$(5.1) \quad |P_{xx} M_{ss} P'_{xx} - \nu W_{xx}| = 0.$$

Then

$$(5.2) \quad T\nu = T \frac{\hat{\beta}' P_{xx} M_{ss} P'_{xx} \hat{\beta}}{\hat{\beta}' W_{xx} \hat{\beta}} = (\sqrt{T} \hat{\beta}' P_{xx}) \frac{M_{ss}}{\hat{\beta}' W_{xx} \hat{\beta}} (\sqrt{T} \hat{\beta}' P_{xx})'.$$

From Theorem 5 of [4] it follows that the asymptotic distribution of  $T\nu$  is the same as that of the quadratic form  $x \frac{E}{\sigma^2} x'$ , where  $x$  has the limiting distribution of  $\sqrt{T} \hat{\beta}' P_{xx}$ , use being made of  $\text{plim}_{T \rightarrow \infty} \hat{\beta}' W_{xx} \hat{\beta} = \sigma^2$ . We have

$$(5.3) \quad dx^i = \beta^j dp_j^i + d\hat{\beta}^j \pi_j^i.$$

Let  $\Upsilon = (I - \beta' \psi)_{.k} (\Theta_{kk})^{-1} (I - \psi' \beta)_{.k}$ . Then

$$(5.4) \quad d\hat{\beta}^j = -v^{jk} \beta^l \pi_k^m e_{mn} dp_l^n.$$

Substituting in (5.3), we obtain

$$(5.5) \quad dx^i = \beta^j dp_j^i - v^{jk} \beta^j \pi_k^m e_{mn} dp_l^n \pi_l^i.$$

Then

$$(5.6) \quad \sigma(x^i, x^q) = \sigma^2(e^{iq} - \pi_k^i \pi_q^k v^{kq}) = \sigma^2 \xi^{iq}$$

say, and  $(\xi^{iq}) = \Xi$ .

Let  $F$  be chosen so  $E = FF'$  and  $F'\Xi F = \Psi$  is diagonal. Since  $E\Xi E\Xi E = E\Xi E$ , the diagonal elements of  $\Psi$  are 1 and 0. The number of elements that are 1 is the rank of  $E\Xi E$ , namely,  $D - H + 1$ , where  $D$  is the number of coordinates of  $v_t$  (the number of coordinates whose coefficients in the selected equation are assumed to be zero). Let  $z = \frac{1}{\sigma} xF$ . Then the asymptotic distribution of  $T\nu$

is the distribution of  $zz'$  where  $z$  is normally distributed with mean zero and covariance matrix  $\Psi$ . It is the  $\chi^2$ -distribution with  $D - H + 1$  degrees of freedom. We observe that  $T \log(1 + \nu)$  and  $TD\lambda$  are asymptotically equal to  $T\nu$ , where  $\lambda$  is the criterion based on small sample theory [2, Theorem 4]. Finally, we note that  $\nu$  is independent of the normalization of  $\beta$ .

**THEOREM 5.** *If Assumptions A, B, F, H, I, K, M, and N are satisfied,  $-2$  times the logarithm of the likelihood ratio criterion,  $-T/2 \log(1 + \nu)$ , the asymptotically equivalent  $T\nu$  and  $TD$  times the small sample criterion,  $\lambda$ , for testing the hypothesis that the number of coordinates with zero coefficients is  $D$  are asymptotically distributed as  $\chi^2$  with  $D - H + 1$  degrees of freedom.*

This theorem indicates how conservative the small sample test is asymptotically, for that test asymptotically is equivalent to using  $T\nu$  as having an asymptotic  $\chi^2$ -distribution with  $D$  degrees of freedom.

**6. Asymptotic behavior of confidence regions based on small sample theory.**

In [2] we deduced confidence regions for  $\beta$  and for  $\beta$  and  $\gamma$  when Assumption E holds. If the normalization of  $\beta$  is

$$(6.1) \quad \beta \Phi_{xx} \beta' = 1,$$

where  $\Phi_{xx}$  is a given matrix, then a confidence region (a) for  $\beta$  of confidence  $\epsilon$  consists of all  $\beta^*$  satisfying (6.1) and

$$(6.2) \quad \frac{\beta^* M_{zs} M_{ss}^{-1} M_{sz} \beta^{*'}}{\beta^* W_{zz} \beta^{*'}} \leq \frac{D}{T - K} F_{D, T-K}(\epsilon),$$

where  $F_{D, T-K}(\epsilon)$  is chosen so the probability of (6.2) for  $\beta^* = \beta$  is  $\epsilon$  and  $K$  is the number of coordinates of  $z_t$  and  $D$  is the number of coordinates of  $v_t$ . A region (b) for  $\beta$  and  $\gamma$  simultaneously consists of  $\beta^*$  and  $\gamma^*$  satisfying (6.1) and

$$(6.3) \quad \frac{\beta^* M_{zu} M_{uu}^{-1} M_{uz} \beta^{*'} + \beta^* M_{zu} \gamma^{*'} + \gamma^* M_{uz} \beta^{*'} + \gamma^* M_{uu} \gamma^{*'} + \beta^* M_{zs} M_{ss}^{-1} M_{sz} \beta^{*'}}{\beta^* W_{zz} \beta^{*'}} \leq \frac{K}{T - K} F_{K, T-K}(\epsilon).$$

We shall now show that even if Assumption E does not hold the regions have asymptotically confidence coefficients  $\epsilon$  and they are consistent under general conditions.

Let  $c = \beta M_{zu} M_{uu}^{-1} + \gamma$ ,  $e = \beta M_{zs} M_{ss}^{-1}$ . We observe from Section 4 that if Assumptions A, B, F, H, K, L, M and N are satisfied, the vectors  $\sqrt{T}c$  and  $\sqrt{T}e$  have asymptotic independent distributions  $N(0, \sigma^2 C^{-1})$  and  $N(0, \sigma^2 E^{-1})$ , respectively. Then  $TcM_{uu}c'/\sigma^2$  and  $TeM_{ss}e'/\sigma^2$  will have asymptotic independent  $\chi^2$ -distributions with  $F(= K - D)$  and  $D$  degrees of freedom, respectively. Also  $\beta W_{zz}\beta'$  approaches  $\sigma^2$  stochastically. By Theorems 5 and 6 of [4], the left-hand sides of (6.2) and (6.3) have asymptotic  $F$ -distributions with  $D$  and  $T - K$  degrees of freedom and  $K$  and  $T - K$  degrees of freedom, respectively.

We shall prove that (a) is consistent for  $\beta$ ; the proof is similar for (b) as a region for  $\beta$  and  $\gamma$ . If we replace  $\beta$  by  $b$  in the definition of  $e$ ,  $eM_{ss}e' = bM_{zs}M_{ss}^{-1}M_{sz}b'$ . For  $b \neq \beta$  we must show that the probability that  $b$  will fall in the confidence region for  $\beta$  approaches zero. The above form approaches  $b\Pi_{zs}E\Pi_{zs}'b'$  in probability. If  $b \neq \beta$  and satisfies (6.1) then  $b\Pi_{zs} \neq 0$  and  $eM_{ss}e'$  has a non-zero limit in probability since  $E$  is positive definite. Thus  $b$  is not in the limiting confidence region.

**THEOREM 6.** *If Assumptions A, B, F, H, I, K, M, and N are satisfied, the confidence regions of Theorem 3 of [2] (including (a) and (b) above) are consistent, and the regions (a) and (b) have asymptotically the confidence levels  $\epsilon$ .*

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